

Connecting Gaze, Scene, and Attention: Generalized Attention Estimation via Joint modeling of Gaze and Scene Saliency

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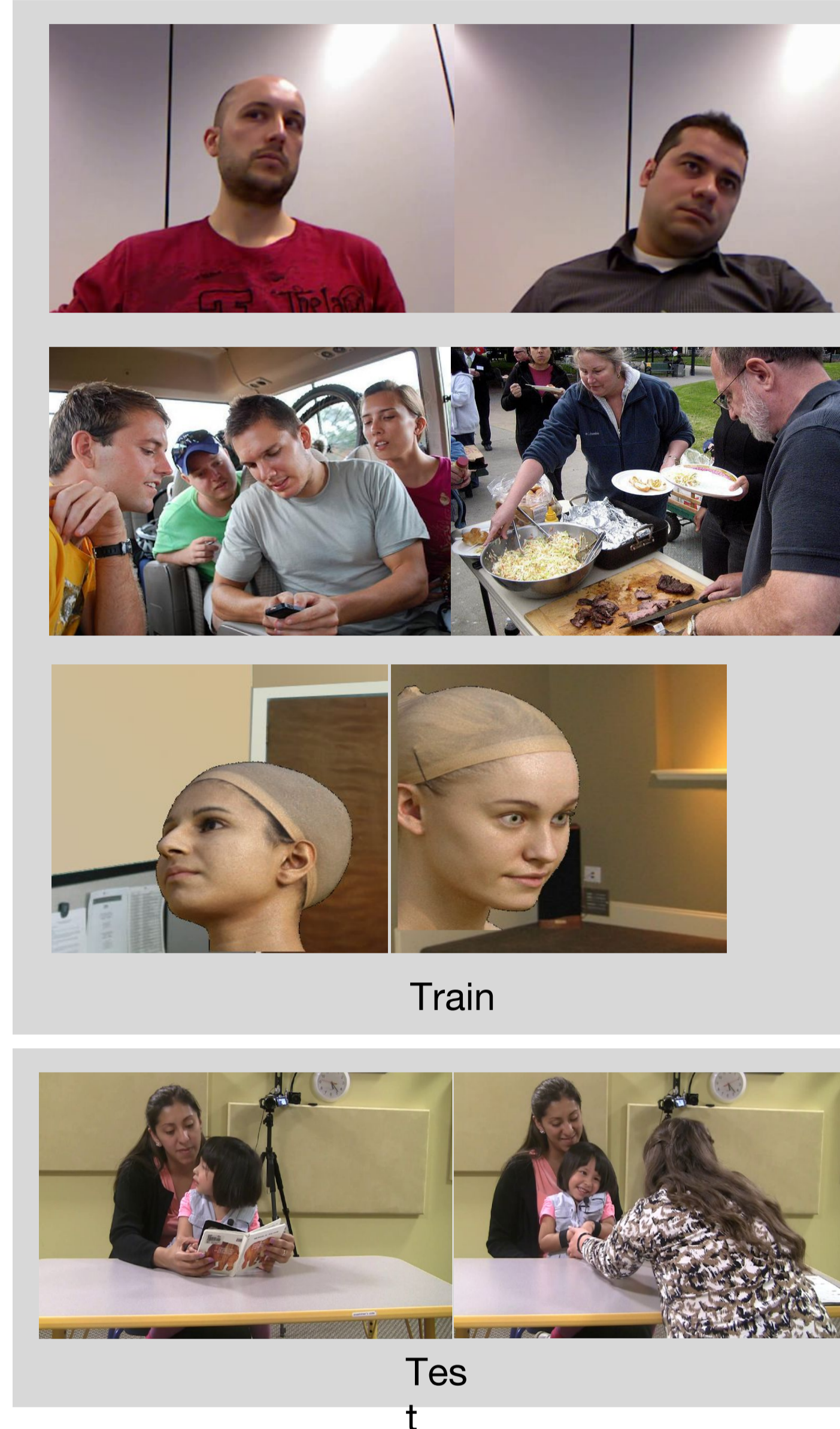
Problem

- Human gaze behaviors are complex in the real world. **Automatically detecting and quantifying various types of visual attention from images** remains an open challenge.
- Current systems have focused on constrained versions of this problem in predetermined contexts.

Our Approach

- We propose the new problem of **“generalized attention estimation”** and **design a system that can model the visual attention of subjects in unconstrained scenarios** which works across most natural scenarios.
- We exploit three public datasets that have been originally collected for different tasks to solve this problem.

Dataset



- EYEDIAP dataset [1]
 - Gaze and head pose variance
 - Target outside, clean background
 - Learn precise gaze angle representation
- GazeFollow dataset [2]
 - Real world pictures
 - Target inside (with our additional annotation)
 - Learn gaze-relevant scene saliency representation
- SynHead dataset [3]
 - Large head pose variation
 - Target outside, arbitrary background
 - Complement the other datasets
- MMDB dataset [4]
 - Naturalistic social interactions
 - Frame-level annotations of subject’s visual targets (with our additional annotation) among many other nonverbal behaviors

Result



GazeFollow dataset (test split)

MMDB dataset

Table 1 Gaze-saliency evaluation on the GazeFollow test set

Method	AUC	L2 Distance	Min Distance
Random	0.504	0.484	0.391
Center	0.633	0.313	0.230
Judd [17]	0.711	0.337	0.250
GazeFollow [23]	0.878	0.190	0.113
Our	<i>0.896</i>	<i>0.187</i>	<i>0.112</i>

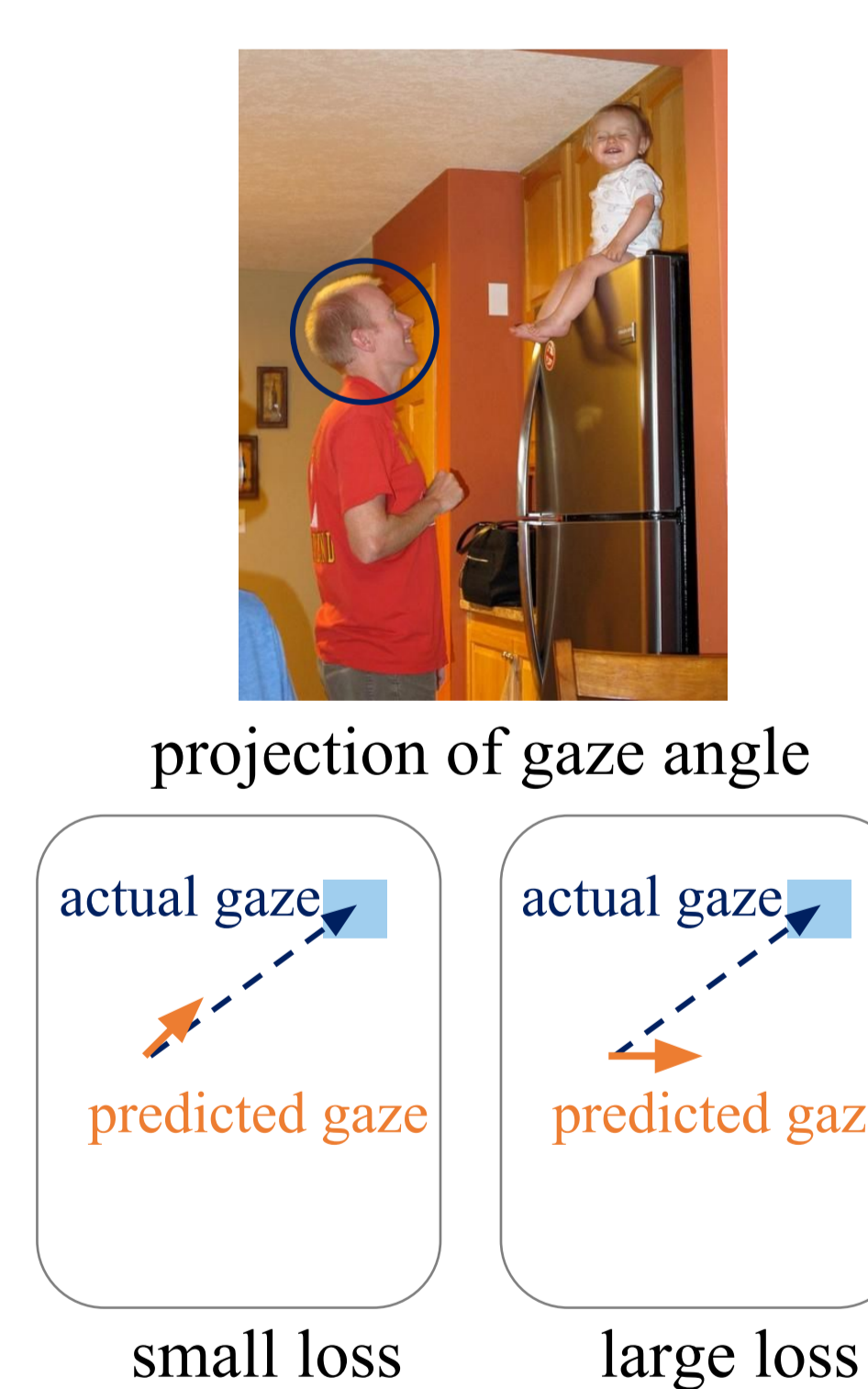
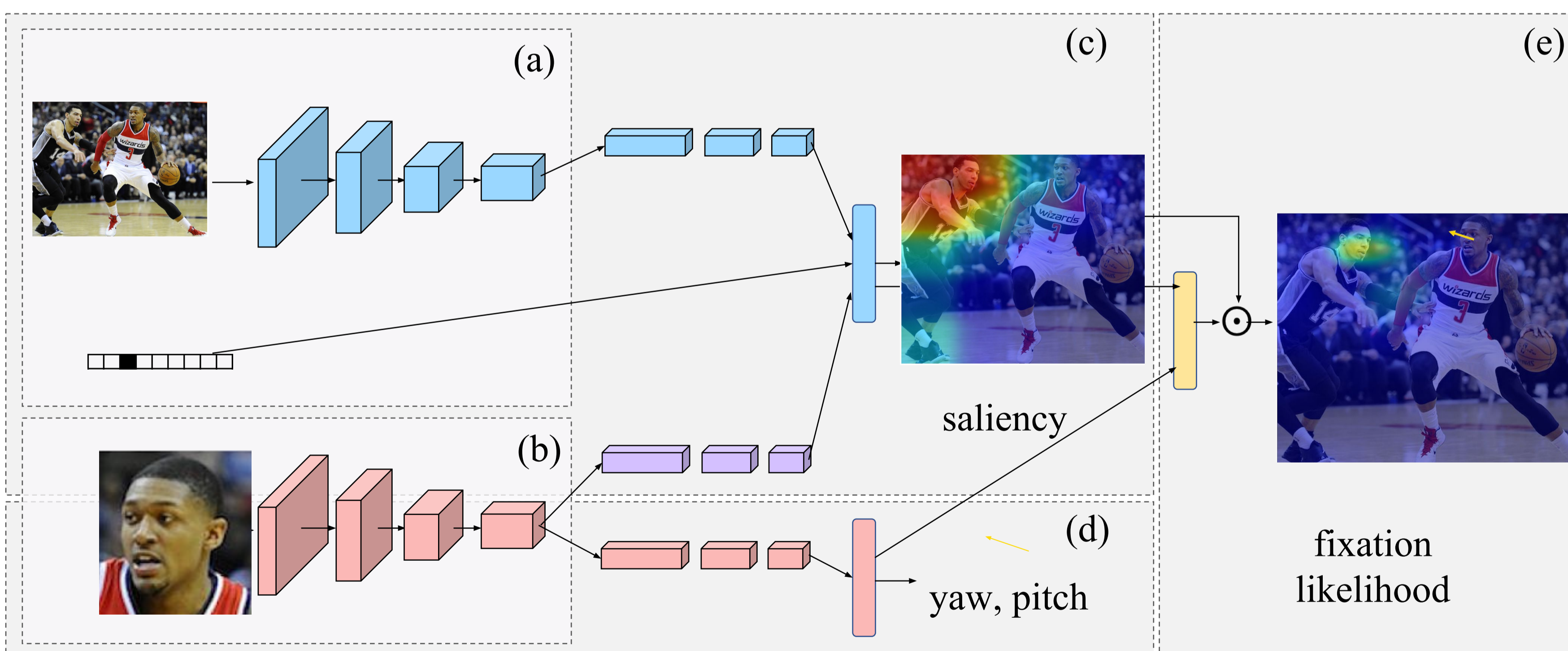
Table 3 Evaluation on MMDB - gaze target grid classification

Grid Size	Method	Precision	Recall
2x2	GazeFollow [23]	0.344	0.715
	Our	0.744	0.851
5x5	GazeFollow [23]	0.210	0.437
	Our	0.614	0.683

Table 4 Evaluation of fixation likelihood on MMDB

Method	Average Precision
SVM with GazeFollow [23]	0.311
SVM with GazeFollow [23]+gaze [32]	0.531
SVM with GazeFollow [23]+headpose [2]	0.620
SVM with gaze [32]+headpose [2]	0.405
SVM with GazeFollow [23]+gaze [32]+headpose [2]	0.624
Random Forest with GazeFollow [23]	0.707
Random Forest with GazeFollow [23]+gaze [32]	0.727
Random Forest with GazeFollow [23]+headpose [2]	0.785
Random Forest with gaze [32]+headpose [2]	0.512
Random Forest with GazeFollow [23]+gaze [32]+headpose [2]	0.773
Our, trained only with GazeFollow dataset	0.737
Our, trained only with GazeFollow and EYEDIAP dataset	0.820
Our final	<i>0.902</i>

Method



Project-and-Compare
➤ When angle is not directly available, a projection of its predicted angle is used as a measure of loss.

- Our model achieves state-of-the-art result on the gaze following task, which consists in identifying the location of the scene the subject is looking at.

Table 2 Gaze angle evaluation on EYEDIAP

Method	Angular Error (degree)
Wood [29]	11.3°
iTracker [18]	8.3°
Zhang [32]	6.0°
Our	6.4°

- Our model also competes with the state-of-the-art on the 3D gaze estimation task

References

- [1] Mora, et al. EYEDIAP: A Database for the Development and Evaluation of Gaze Estimation Algorithms from RGB and RGB-D Cameras. ETRA 14.
- [2] Recasens, et al. Where are they looking? NIPS 15.
- [3] Gu, et al. Dynamic Facial Analysis: From Bayesian Filtering to Recurrent Neural Network. CVPR 17.
- [4] Rehg, et al. Decoding Children’s Social Behavior. CVPR 13.

- Input = full scene image, a person’s face location whose visual attention we want to predict, and the close-up face image.
- Scene and face images go through separate convolutional layers in such a way that (a) (b) and (c) contribute to saliency, and (b) and (d) contribute to gaze angle prediction. In the last layer, the final feature vectors for two tasks are combined to estimate how likely the person is actually fixating at a gaze target in the frame.
- Loss = Cross Entropy + Euclidean + Project-and-Compare.